

Staging calculi

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Our motivation: program generation

- ▶ flexible: scope mismatch, let insertion
- ▶ convenient: first-class delimited continuations
- ▶ safe: prevent scope extrusion

Our need: a typed staging calculi

- ▶ call by value, with small-step semantics
- ▶ splice open code and run closed code
- ▶ cross-stage persistence

Embarrassment of riches: $\lambda^U, \lambda^\square, \lambda^{S^4}, \lambda^\circ, \lambda^{\circ\square}, \lambda^\alpha, \lambda^i_{\text{let}}$

- ▶ Relationship unclear
- ▶ None satisfactory
- ▶ No effects

Goals

With hindsight:

1. Compile a definite reference to staged calculi, to reduce rummaging through the literature.
 - ▶ Which calculus supersedes which?
 - ▶ How do they compare?
2. Design a common calculus or calculi substrate.
 - ▶ At least share notation.
 - ▶ Add or remove features such as 'run' and polymorphism.
3. Model real implementations such as MetaOCaml.
4. Compile a database of mechanized calculi.

Motivation

We want to prevent

```
let code = let x = ref .<1>. in
            let _ = .<fun v -> .~(x := .<v>. ; .<()>.)>. in
            !x
► val code: ('a, int) code = .<v_1>.
```

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let code = let x = ref .<1>. in
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```

► val code: ('a, int) code = .<v_1>.
.!code

► Unbound value v_1
Exception: Trx.TypeCheckingError.

This example is contrived; we can show a more realistic example.

These examples occur in MetaOCaml, which has mutable state, exceptions, and first-class delimited continuations.

No real model.

Comparison

	Typed	Splice	Run	Persist	Call by	Steps
λ^U	no	yes	yes	values	name	big
$\lambda^\square, \lambda^{S4}$	yes	no	yes	no	?	?
λ°	yes	yes	no	no	?	?
$\lambda^{\circ\square}$	yes	yes	some	variables	value	small
λ^a	yes	yes	yes	yes	name	big
λ^i_{let}	yes	yes	yes	yes	name	big

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Cross-stage persistence:

- ▶ only variables? only values?
- ▶ evaluated when code is built? is run?
- ▶ open code? `.<fun x -> .%(<x>.)>.`
- ▶ restricted by type?

Mechanization: how to type the context $(a).<\text{fun } x \rightarrow \sim []>.$

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